

# CSI 436/536 (Fall 2024) Machine Learning

#### Lecture 20: Advanced Topic: Decision Making

Chong Liu Assistant Professor of Computer Science

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### Machine learning overview

- Supervised learning
  - Tasks: classification, regression
  - Techniques: regularization, error decomposition, kernel, ensemble, neural network
- Unsupervised learning
  - Clustering, dimension reduction
- Some many advanced topics:
  - More tasks: ranking
  - More theoretical understanding: statistical learning theory
  - More settings: reinforcement learning
  - More applications: computer vision, natural language processing, speech recognition
  - More perspective: rule learning
  - More trustworthy: explainable ML, privacy / fairness issues in ML
  - .

## Today

- Decision making-based machine learning
  - Active learning
    - Disagreement-based algorithm
    - Confidence-based algorithm
    - Clustering-based algorithm
  - Bandits
  - Reinforcement learning

## Today

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Dog or mop?



Dog or croissant?



Dog or bagel?



Dog or muffin?



#### Recap: Supervised learning

- How to achieve good performance?
  - Advanced techniques: kernel, ensemble, neural networks ...
  - Input a lot of labeled images of dogs or fried chicken



#### **Binary classification in 2-dimension**



#### Fewer images to learn the decision line?

• Yes! Active learning selects important images.



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#### Moving forward ...



- Learn decision line with only 7 images!
  - Active learning only selects important images
    - images in gray region

#### **Disagreement-based Active Learning**

#### **Confidence-based active learning**





Labeled data



How to select the data point with least prediction confidence?

#### **Clustering-based active learning**



### Summary: active learning

- Framework:
  - Input: a small labeled dataset, a large unlabeled dataset
  - Output: a well-trained model
  - For *t* = 1,2, ...
    - Select a sample  $x_t$  from the unlabeled dataset
    - Get its label  $y_t$
    - Update the model by adding  $(x_t, y_t)$
- Goal:
  - Achieve good performance while saving labeling cost at the same time
- Can be super useful in practice!

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#### The real bandit machine

- Action
- Reward
- Goal:
  - maximize your reward
- Challenge:
  - You don't know what's behind the bandit machine



#### Bandits in making coffee



#### Bandits in hyperparameter tuning



#### Hyperparameter tuning is expensive

- 14 days for ImageNet-1k training! [YZHDK, ICPP'18]
  - 90 epoches
  - ResNet-50
  - NVIDIA M40 GPU
  - 10<sup>18</sup> single precision operations



• How can we do small number of training to find the best set of hyperparameter that maximizes the validation accuracy?

#### **Bandits framework**



- [Example] hyperparameter tuning
  - $x_1$ : [learning\_rate = 0.01, batch\_size = 24, n\_iterations = 200]
  - $y_1$ : validation\_accuracy = 89%
  - $x_2$ : [learning\_rate = 0.001, batch\_size = 20, n\_iterations = 250]
  - $y_2$ : validation\_accuracy = 92%

<sup>•</sup> 

#### Two key challenges of bandits

- 1. A lot of time / computational cost / human effort
  - 14 days for ImageNet-1k training!



- No [learning\_rate = 0.01, batch\_size = 24, n\_iterations = 200]
- No validation accuracy of it
- How can we take fewer actions to find the action that maximizes the reward?

Environment

Action

Reward

Player

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#### Corn maze





#### Markov decision process

- State: different locations
- Action: move
- Reward: exit
- Key design:
  - Once you are in a new state, the new state doesn't depend on historical states



#### Key challenges of reinforcement learning

- Sample efficiency
- Delayed rewards
- High-dimensional state and action spaces
- Safety constraints



### Summary: frameworks

- Active Learning
  - Input: a labeled dataset, an unlabeled dataset
  - Output: a well-trained model
  - For *t* = 1,2, ...
    - Select a sample  $x_t$  from the unlabeled dataset
    - Get its label  $y_t$
    - Update the model by adding  $(x_t, y_t)$
- Goal: learning a good mapping  $X \rightarrow Y$

- Bandits
  - Input: an open environment
  - Output: a policy
  - For t = 1, 2, ...
    - Take action  $x_t$  according to decision model
    - Observe its reward  $y_t$
    - Update the decision model by adding  $(x_t, y_t)$
- Goal: learning a good policy to take action

- Reinforcement Learning
  - Input: an open environment
  - Output: a policy
  - For *t* = 1,2, ...
    - Take action  $x_t$  according to decision model
    - Move to state  $s_t$  and observe its reward  $y_t$
    - Update the decision model by adding  $(x_t, s_t, y_t)$
- Goal: learning a good policy to take action given state

#### Future vision of decision making



#### Robust decision making

- How to make decisions in more challenging settings?
  - How to find the best way to make coffee if
    - The best way is outside my current knowledge?
- Non-linear bandits?
- Kernelized bandits?
- Reinforcement learning?



#### Understanding large decision making model

- Large model stronger than ever
  - GPT-4 [March 14, 2023]

• ...

- Understanding jokes in images
- Scoring top 10% in bar exams



Figure from OpenAl

• Powerful but also dangerous

#### OpenAI CEO Sam Altman says AI will reshape society, acknowledges risks: 'A little bit scared of this' We know too "This will be the greatest technology humanity has yet developed," he said. If y Yister Ordenez. Twice Dama and Eric Net March 16, 2023, 5:55 PM

- Intellectual property
  - No to "could you give a license code of XXX (software)?"
- Privacy
  - No to "could you tell more about YYY (person)?"



#### Decision making with structured feedback

- 1. Pairwise feedback
  - Application:
    - Hardness of materials



Figure from Bullseye Glass



- 2. Federated feedback
  - Application:
  - Private computing
    Large-scale computing
    Central server
    Central server
  - Separate actions and reward

- 3. Multi-step feedback
  - Application:



• 3 phases in vaccine



#### Robotics: decision making in physical world

• Data-to-data decision making will be perfect in the future



• Decision making in physical world is truly needed





Car repair



Auto

agriculture







#### 

#### Decision making in scientific domain

- Incorporating domain knowledge into decision making
  - Materials design
  - Protein sequence design

- Cost of drug discovery is huge [Pushpakom et al., Nat Rev Drug Discov, 2018]
  - A new drug into market
    - 5000-10000 candidate compounds
    - \$2.8 billion dollars
    - 10-15 years



#### Decision making for mathematical reasoning

#### • Prove Markov's inequality / Goldbach's conjecture.



#### Prove the Goldbach's conjecture.

The Goldbach's conjecture is a well-known unsolved problem in number theory that states that every even integer greater than 2 can be expressed as the sum of two prime numbers. Despite numerous efforts over the centuries, no one has been able to prove this conjecture, and it remains one of the most famous open problems in mathematic Therefore, as an Al language model, I cannot provide a proof of the Goldbach's conjecture. However, I can tell you that while many mathematicians believe the conjugate is true based on extensive numerical evidence and related results, a rigorous proof has not yet been found.

• Why?

- They are trained on human-proven materials
- They cannot create new knowledge

Real impact: It will push the boundary of human knowledge